

# SIPART PS2 electropneumatic positioners

## SIPART PS2, SIPART PS2 PA, SIPART PS2 EEx d and SIPART PS2 EEx d PA

### Application, design

#### Application

The SIPART PS2 electropneumatic positioner is used to control the final control element of pneumatic linear or part-turn actuators. The electropneumatic positioner moves the actuator to a valve position corresponding to the setpoint. Additional function inputs can be used to block the valve or to set a safety position. A binary input is present as standard in the basic device for this purpose.

The SIPART PS2 positioner is characterized by significant advantages compared to conventional devices, such as:

- Only one device version for linear and part-turn actuators
- Simple operation and programming using three keys and a two-line LCD
- Automatic startup function with self-adjustment of zero and span
- Manual operation without additional equipment
- Selectable or freely-programmable characteristics
- Diagnostic functions for valve or actuator (see page 5/4)
- Minimum air consumption
- Selectable setpoint and manipulated variable limiting
- Programmable "tight shut-off function".

The SIPART PS2 positioner is available:

- In a plastic or metal casing for single-action actuators
- In a plastic casing for double-action actuators
- For non-hazardous or hazardous applications in designs
  - as intrinsically-safe device (EEx ia/lb) or
  - in flameproof casing (EEx d)

and in the versions:

- With 0/4 to 20 mA communication using HART signals (option)
- With PROFIBUS-PA communications interface (EEx ia).

#### Design

The SIPART PS2 positioner is a digital field device with a highly-integrated microcontroller.

The positioner consists of the following components:

- Casing and cover
- PCB with corresponding electronics with or without communication via HART or with electronics for communication according to the PROFIBUS-PA specification, IEC 1158-2; bus-supplied device
- Actuator travel detection system
- Terminal housing with screw terminals
- Pneumatic valve manifold with piezoelectric valve precontrol.

The valve manifold is located in the housing, the pneumatic connections for the inlet air and the positioning pressure on the right-hand side. A pressure gauge block and/or a safety solenoid valve can be connected there as options. The circuit board container in the casing provides slots for separately ordered boards with the following functions:

- I<sub>v</sub> module:
  - Position feedback as a two-wire signal 4 to 20 mA.
- Alarm module (3 outputs, 1 input):
  - Signalling of two limits of the travel or angle by binary signals. The two limits can be set independently as maximum or minimum values.
  - Output of an alarm if the setpoint position of the final control element is not reached in automatic mode or if a device fault occurs
  - Second binary input for alarm signals of for triggering safety reactions or for blocking/signalling function or safety position.



Fig. 5/1 SIPART PS2 or SIPART PS2 PA electropneumatic positioner



Fig. 5/2 SIPART PS2 EEx d or SIPART PS2 EEx d PA electropneumatic positioner in flameproof casing



Fig. 5/3 SIPART PS2 or SIPART PS2 PA in stainless steel casing

All signals in the I<sub>v</sub> and alarm modules as well as the SIA module (see page 5/3) are electrically isolated from one another and from the basic unit. The outputs indicate self-signalling faults.

# SIPART PS2 electropneumatic positioners

## SIPART PS2, SIPART PS2 PA, SIPART PS2 EEx d and SIPART PS2 EEx d PA

Design

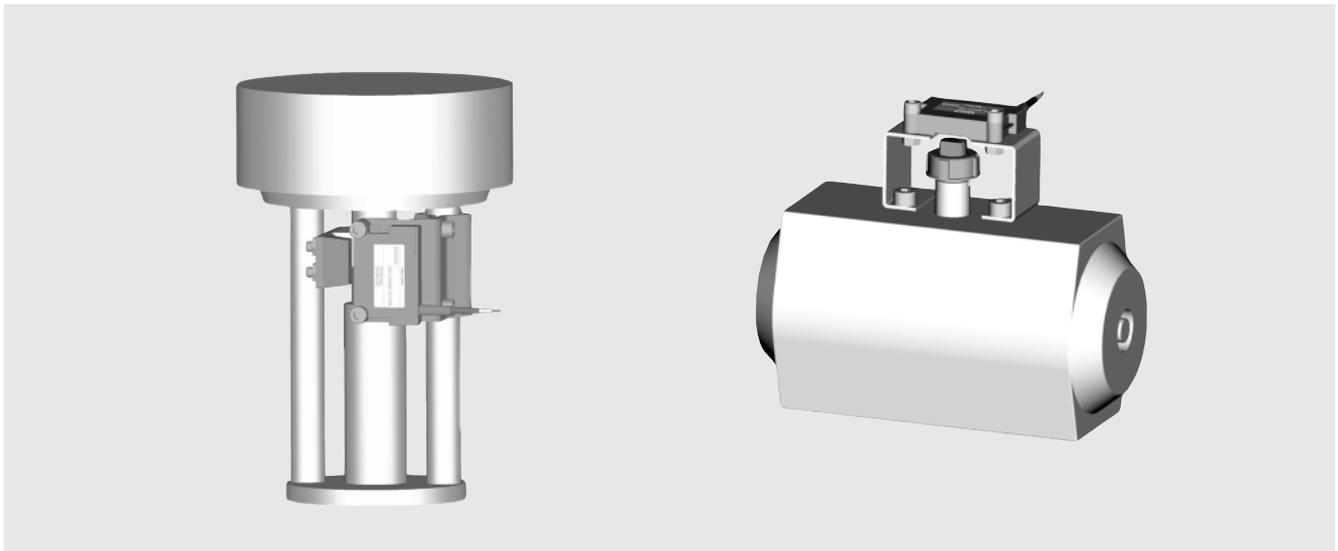


Fig. 5/4 Non-contacting position sensor (NCS) for linear actuator (left) and part-turn actuator (right)

### Stainless steel casing for extreme ambient conditions

The SIPART PS2 (including the EEx d version) is available in a stainless steel casing (see Fig. 5/3) for use in particularly aggressive environments (e.g. offshore operation, chlorine plants etc.). The device functions are the same as with the basic device.

### Limit signalling via slot-type initiators (SIA module)

Two limits can be signalled redundantly as NAMUR signals (DIN 19 234) by slot-type initiators using an easy-to-fit module. The module additionally contains an alarm output (see alarm module).

### Separate connection of actuator travel detection system and controller unit

The actuator travel detection system and controller unit can be connected separately for all casing versions of the SIPART PS2. Measurement of the travel or angle is carried out as usual directly on the actuator by means of the corresponding attachment set and e.g. a SIPART PS2 casing which contains the travel detection system (internal potentiometer and sliding clutch). The controller unit can then be fitted a certain distance away, e.g. on a mounting pipe or similar, and is connected to the travel detection system via an electric cable and to the actuator via one or two pneumatic lines (see Fig. 5/5). Such a split design is frequently advantageous if the ambient conditions at the fitting exceed the specified values for the positioner, e.g.:

- Extremely high/low ambient temperature
- Extremely high vibrations
- Nuclear (e.g. neutron) radiation.

The use of linear potentiometers (10 kΩ resistance) is recommendable for very small actuators with a short valve travel since, on the one hand, the space required by the linear potentiometer is very small and, on the other, the transmission characteristic is optimum for a small travel.

### Non-contacting position sensor (NCS)

The actuator travel detection unit can also consist of a non-contacting position sensor instead of a potentiometer. All coupling elements are omitted such as coupling wheel and driver pin with part-turn actuators or lever and pick-up bracket with linear actuators.

This results in:

- Even greater resistance to vibration and shock
- No wear of sensor
- Problem-free mounting on very small actuators
- No hysteresis with very small travels.

The sensor does not require an additional power supply, i.e. SIPART PS2 can be operated in a two-wire system. The NCS (Non-Contacting Position Sensor) consists of a potted sensor housing which must be mounted permanently and a magnet which is mounted on the spindle of linear actuators or on the shaft butt of part-turn actuators.

The installation of a special EMC filter module is necessary in the positioner (controller unit) to guarantee EMC according to EN 50 081-1 or EN 50 082-2 when using external sensors (see Ordering data: EMC filter module).

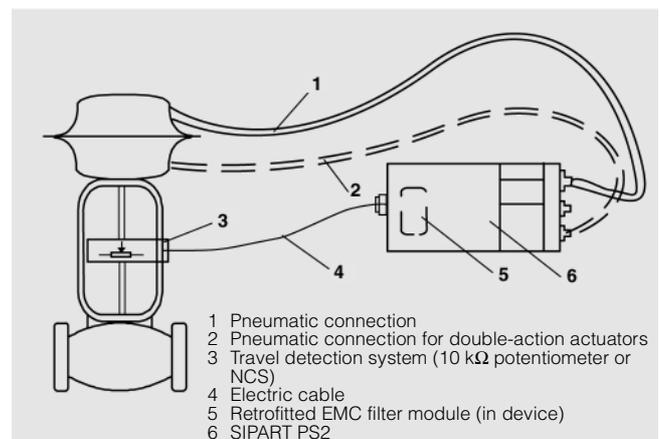


Fig. 5/5 Separate mounting of actuator travel detection system and controller unit

# SIPART PS2 electropneumatic positioners

## SIPART PS2, SIPART PS2 PA, SIPART PS2 EEx d and SIPART PS2 EEx d PA

### Mode of operation

#### Mode of operation

The SIPART PS2 electropneumatic positioner works in a completely different way to normal positioners.

Comparison of the setpoint and the actual value takes place electronically in a microcontroller. If the microcontroller detects a deviation, it uses a 5-way switch procedure to control the piezoelectric valves, which in turn regulate the flow of air into the actuating chambers. When connected in a two-wire system, the SIPART PS2 draws its power exclusively from the 4 to 20 mA setpoint signal. The electric power is also connected via the two-wire bus signal with PROFIBUS mode (SIPART PS2 PA).

The way the SIPART PS2 works, together with its integrated additional functions, offer the user considerable benefits in the installation and operation of the positioner:

- Simple installation and largely automatic commissioning means time savings and guarantees reliable operation
- An on-line adaptation procedure means very high-quality control even under unfavorable operating conditions
- The SIPART PS2 is not affected by vibration as it has very few moving parts
- The effect of temperature and compressed air pressure on the SIPART PS2 positioner is negligible
- Maintenance-free operation
- The valve position can be adjusted manually with the help of a display and keyboard. A separate current source is not required
- The firmware contained in the SIPART PS2 positioner provides a number of functions that can be activated simply by configuring the positioner accordingly, e.g. valve characteristic, stroke limitation or split range operation
- The "tight shut-off" function ensures maximum positioning pressure on the valve seat
- Compressed air consumption when operating the positioner is negligible compared to a traditional positioner.

The SIPART PS2 positioner is fitted to the linear or part-turn actuator using an appropriate mounting assembly. The linear or rotary motion of the actuator is detected by the mounting assembly and transferred via a rigid connection to a potentiometer made of a wear-resistant plastic conductive material.

The angular error of the pick-up in cases where the assembly is mounted on a linear actuator is corrected automatically.

The microprocessor then outputs an electric control command to the piezoelectric valve in accordance with the magnitude and direction of the deviation (deviation between setpoint  $w$  and control output  $x$ ).

The piezoelectric valve converts the command into a pneumatic positional increment. The positioner outputs a continuous signal in the area where there is a large control deviation (high-speed zone); in areas of moderate control deviation (slow-speed zone) it outputs a sequence of pulses. No positioning signals are output in the case of a small control deviation (adaptive or variable dead zone).

#### Pneumatic valve manifold with piezoelectric valve precontrol

The valve manifold is characterized by an extremely long service life. The pilot element is a piezoelectric bending converter which switches the pneumatic main control unit. The piezoelectric valve can release very short control pulses because of its low mass. A high positioning accuracy can then be achieved.

#### Three explosion-proof versions

The basic version of the device is available in an intrinsically-safe design with degree of protection EEx ia/ib or in a non-intrinsically-safe design for zone 2 (see Technical data for intrinsically-safe versions).

An non-intrinsically-safe application is permissible in zone 1 for the SIPART PS2 EEx d flameproof version (also in zone 0 with FM certification, see Technical data). It is then permissible to use all option modules.

#### Operation and monitoring with the SIMATIC PDM communications program

The SIMATIC PDM program is available for communication via the HART interface and also for the PROFIBUS-PA coupling.

The SIMATIC PDM communications software permits easy remote operation and monitoring via a PC or laptop. The positioner can also be configured using this program. Parameters which provide important information for maintenance and fault diagnosis of the complete unit can additionally be determined using process data and comparison data. When operating the SIPART PS2 via the HART interface, the connection to the PC or laptop is made directly to the two-wire cable to the SIPART PS2 positioner via a HART modem connected to the COM interface. The signals required for communication according to the HART protocol are superimposed on the current signal according to frequency shift keying.

#### Commissioning

Commissioning (initialization) is carried out automatically to a large extent.

During initialization, the microcontroller automatically determines the zero, full-scale value, direction of action and positioning speed of the actuator. It uses these to determine the minimum pulse time and the dead zone, thus optimizing the control.

The pneumatic actuator can also be operated manually using the pushbuttons and the LCD of the SIPART PS2 positioner.

#### Monitoring and diagnostics functions for positioners, actuators and valves

The SIPART PS2 (6DR5...) has various monitoring functions with which changes on the actuator and valve can be detected and signalled if applicable when a selectable limit has been exceeded. This information may be important for diagnosis of the actuator or valve. The measured values (some of whose limits can be adjusted) to be determined and monitored include:

- Travel integral
- Number of changes in direction
- Alarm counter
- Self-adjusting dead zone
- Valve limit position (e.g. wear of valve seat)
- Operating hours (also according to temperature classes) as well as min./max. temperatures
- Operating cycles of piezoelectric valves
- Valve positioning time
- Actuator leakages.

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## SIPART PS2, SIPART PS2 PA, SIPART PS2 EEx d and SIPART PS2 EEx d PA

Mode of operation

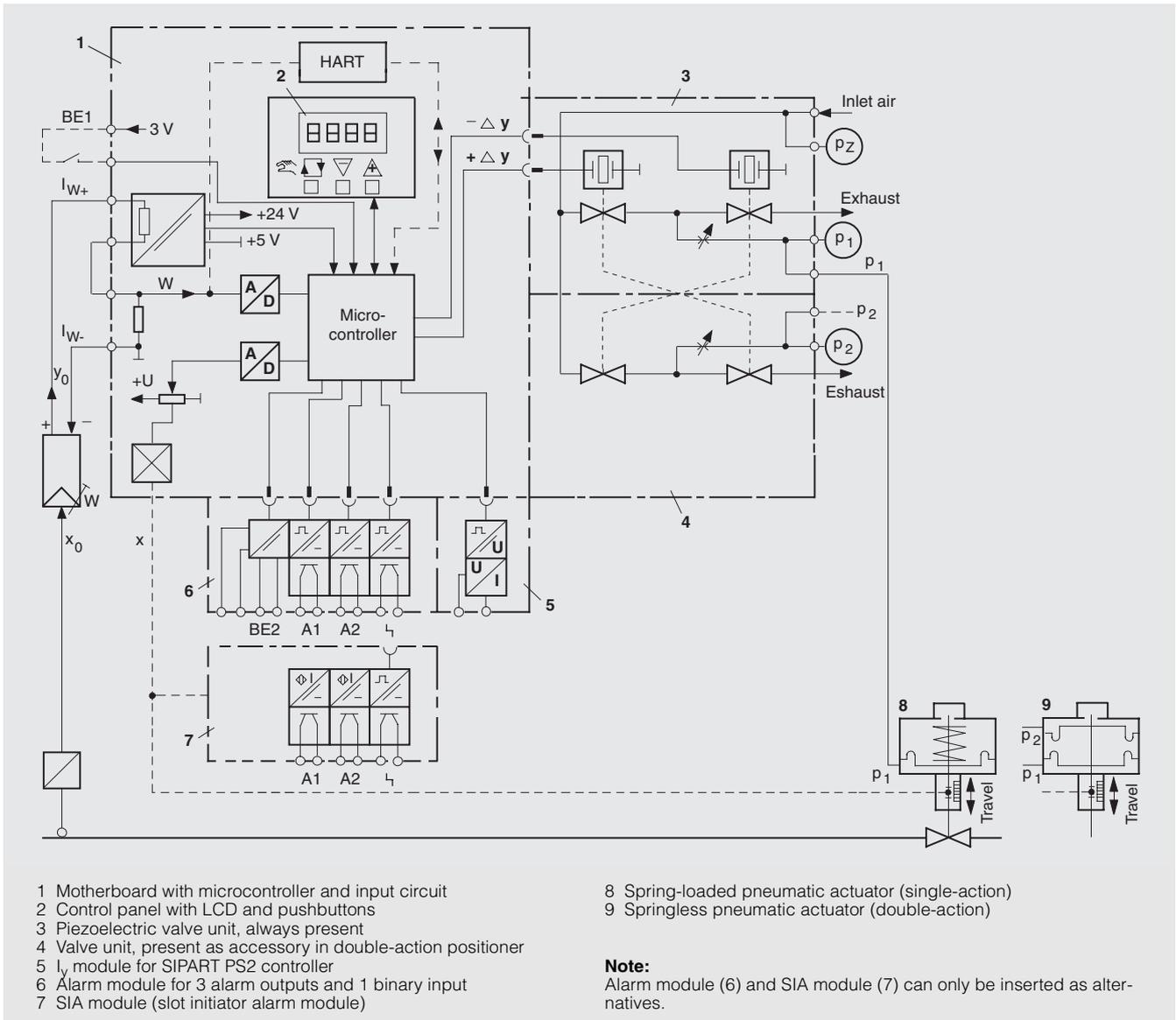


Fig. 5/6 SIPART PS2, electropneumatic positioner, function diagram

# SIPART PS2 electropneumatic positioners

## SIPART PS2, SIPART PS2 PA, SIPART PS2 EEx d and SIPART PS2 EEx d PA

### Mode of operation

#### Electric connection of two-wire devices (6DR50.., 6DR51..)

Devices of types 6DR50.. and 6DR51.. are operated in a two-wire system.

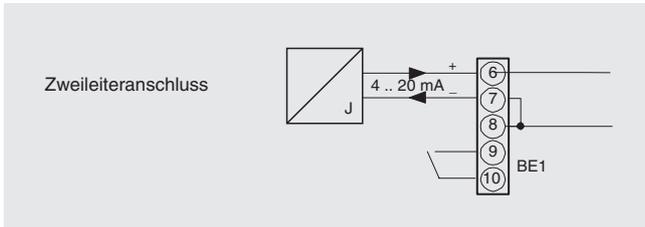


Fig. 5/7 SIPART PS2 electropneumatic positioner, input circuit for 6DR50.. and 6DR51..

#### Electric connection of PROFIBUS-PA devices (6DR41..)

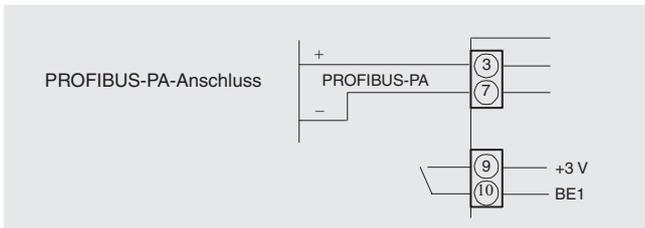


Fig. 5/8 SIPART PS2 PA electropneumatic positioner, input circuit for 6DR41..

#### Electric connection of two/three/four-wire devices (6DR52..)

Devices of type 6DR52.. can be operated in a two-wire, three-wire or four-wire system.

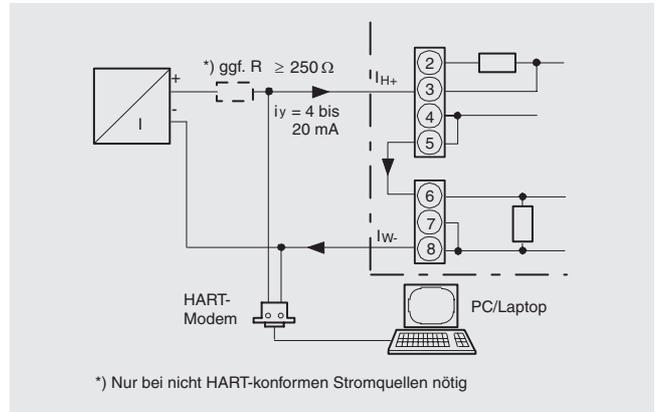


Fig. 5/9 SIPART PS2 electropneumatic positioner, example of connection for communication with HART for 6DR52..

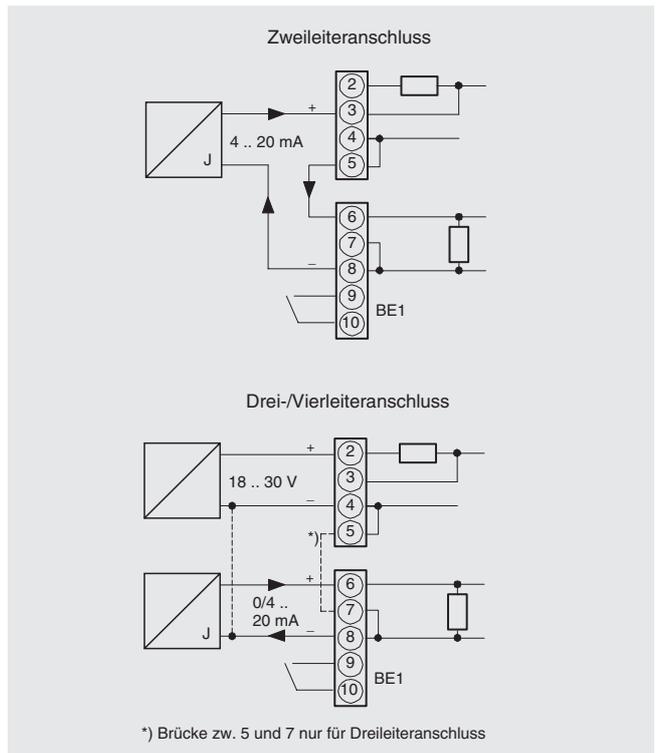


Fig. 5/10 SIPART PS2 electropneumatic positioner, input circuits for 6DR52..

# SIPART PS2 electropneumatic positioners

## SIPART PS2, SIPART PS2 PA, SIPART PS2 EEx d and SIPART PS2 EEx d PA

### Mode of operation, configuring

#### SIMATIC PDM

Task	Parameterization, startup and diagnosis of process devices using PROFIBUS-DP, PROFIBUS-PA and HART interfaces
Required computer hardware	Personal computer/programming device with Pentium processor and 32 Mbyte RAM (64 Mbyte or more recommended)
Operating system	Windows 95, Windows NT
With integration in STEP 7	STEP 7, matching the SIMATIC PDM version
Memory requirements with SIMATIC PDM	Approx. 10 Mbyte, plus 70 Mbyte for SIMATIC PDM without option "Integration in STEP 7"
PROFIBUS-DP connection For PG 720/740/760 programming device For personal computer	Built-in MPI interface Communications processor CP 5511 6GK1 551-1AA00 CP 5611 6GK1 561-1AA00 Required drivers are included in delivery of SIMATIC PDM and in STEP 7
Transition from PROFIBUS-DP to PROFIBUS-PA	DP/PA coupler, Ex version: 6ES7157-0AD00-0XA0, DP/PA coupler, non-Ex version: 6ES7157-0AC00-0XA0, DP/PA link: 6ES7157-0AA00-0XA0
Transition from PROFIBUS-DP to HART	IM 153-2 interface module 6ES7153-2AA01-0XB0, HART analog input module 6ES7331-7TB00-0AB0
HART point-to-point connection	Via HART modem 7MF4997-1DA

» » Input Value			
Direction	Rising		Loaded
Lower Value	0	%	Loaded
Upper Value	100	%	Loaded
Unit (Input)	%		Loaded
Setpoint Cut-Off CLOSE	0	%	Loaded
Setpoint Cut-Off OPEN	100	%	Loaded
Tight closing	Not active		Loaded
» » Working Range			
Lower Value	0	%	Loaded
Upper Value	100	%	Loaded
Unit (Output)	%		Loaded
Lower Limit Valve Position	0	%	Loaded
Upper Limit Valve Position	100	%	Loaded
Y normalization:	to mech. travel		Loaded
» » Characterization			
Characterization Type	Linear		Loaded
» » Output			
Alarm Output	No function		Loaded
Fault output	Fault		Loaded
Mode (Response Threshold)	AUTO		Loaded
Response Threshold	0,1	%	Loaded
Mode (Delay Time)	AUTO		Loaded
Delay Time	1	s	Loaded
» » Output Limits			
Alarm 1	10	%	Loaded
Alarm 2	90	%	Loaded
» » Performance Characteristics			
Mode (Deadband)	AUTO		Loaded
Deadband	1,0	%	Loaded
» » Power Loss			
Actuator action	Not initialized		Loaded
Fail Safe Mode	Fail Safe Value is used as control regulator input		Loaded
Fail Safe Time	30	s	Loaded
Fail Safe Default Value	0	%	Loaded
» » Travel Time			
Mn. Travel Time CLOSE	5,10	s	Loaded
Mn. Travel Time OPEN	5,3	s	Loaded
Travel Time CLOSE	0	s	Loaded
Travel Time OPEN	0	s	Loaded
Mode (Travel Time)	MAN		Loaded

Fig. 5/12 SIMATIC PDM, parameter table

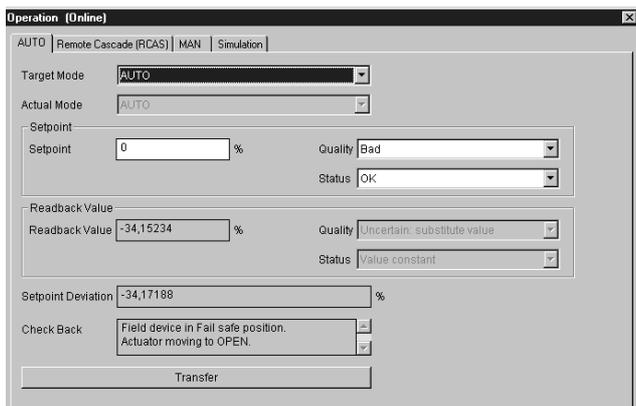


Fig. 5/11 SIMATIC PDM, measured-value display

#### Configuring

The following settings can be configured in configuring mode as required, e.g. with SIPART PS2:

- Input current range 0 to 20 mA or 4 to 20 mA
- Rising or falling characteristic at the setpoint input
- Positioning speed limit (setpoint ramp)
- Split-range operation; adjustable start-of-scale and full-scale values
- Response threshold (dead zone); self-adjusting or fixed
- Direction of action; rising or falling output pressure with rising setpoint
- Limits (start-of-scale and full-scale values) of positioning range
- Limits (alarms) of the final control element position; minimum and maximum values
- Automatic "tight shut-off" (with adjustable response threshold for 6DR5...)
- The travel can be corrected in accordance with the valve characteristic. The following can be selected:
  - Linear characteristic
  - Equal-percentage characteristic 1: 25, 1: 33 and 1: 50
  - Inverse equal-percentage characteristic 1: 25, 1: 33 and 1: 50
  - Any characteristic, to be entered as a polygon with 21 interpolation points.
- Function of binary inputs
- Function of alarm output.

The SIPART PS2 and SIPART PS2 PA positioners are configured differently.

# SIPART PS2 electropneumatic positioners

## SIPART PS2, SIPART PS2 PA, SIPART PS2 EEx d and SIPART PS2 EEx d PA

### Configuring

#### SIPART PS2 and SIPART PS2 EEx d configurations

Parameter name	Function	Parameter values	Dimension
1. YFCT	Type of actuator: part-turn/linear - Part-turn actuator - Linear actuator - Linear actuator without sine-wave correction - Part-turn actuator with NCS - Part-turn actuator with NCS, reverse direction	turn WAY LWAY ncSt -ncSt	
2. YAGL <sup>1)</sup>	Rated angle of feedback	90 ° 33 °	De-grees
3. YWAY <sup>2)</sup>	Travel range 5 to 130 mm - None - Short lever 33° - Short lever 90° - Long lever 90°	OFF 5/10/15/20 25/30/35 40/50/60/70/90/ 110/130	mm
4. INITA	Initialization (automatic)	noini no / ##.# Strt	
5. INITM	Initialization (manual)	noini no / ##.# Strt	
6. SCUR	Current range of setpoint 0 to 20 mA 4 to 20 mA	0 MA 4 MA	mA
7. SDIR	Setpoint direction rising Setpoint direction falling	riSE FALL	
8. SPRA	Start-of-scale for split range setpoint	0.0 to 100.0	%
9. SPRE	Full-scale for split range setpoint	0.0 to 100.0	%
10. TSUP	Setpoint ramp OPEN	Auto 0 to 400	s
11. TSDO	Setpoint ramp CLOSED	0 to 400	s
12. SFCT	Setpoint function - Linear - Equal percentage - Equal percentage, reversed - Freely adjustable	Lin 1:25, 1:33, 1:50 1:25, 1:33, 1:50 FrEE	
13. SL0 <sup>3)</sup> 14. SL1 . . . 32. SL19 33. SL20 <sup>3)</sup>	Setpoint interpolation points at 0 %, 5 %, ... 95 %, 100 %	0.0 to 100.0	%
34. DEBA	Controller dead zone	Auto 0.1 to 10.0	%
35. YA	Start of manipulated variable limit	0.0 to 100.0	%
36. YE	End of manipulated variable limit	0.0 to 100.0	%
37. YNRM	Manipulated variable scaling Mech. travel Flow	MPOS FLOW	
38. YDIR	Manipulated variable direction for display Rising Falling	riSE FALL	
39. YCLS	"Tight shut-off" with man. variable  None Only up Only down Up and down	no uP do uP do	

- 1) 33° cannot be set if "turn" is selected.  
 2) Parameter only appears if 1. YFCT=turn has been selected.  
 3) Interpolation points only appear if 12.SFCT=FrEE has been selected.  
 4) NC means: action with opened switch or Low level.  
 NO means: action with closed switch or High level.  
 5) Normal means: High level without fault.  
 Inverted means: Low level without fault.

Parameter name	Function	Parameter values	Dimension
40. YCDO	Value for "tight shut-off", down	0.0 to 100.0	%
41. YCUP	Value for "tight shut-off", up	0.0 to 100.0	%
42. BIN1 <sup>4)</sup>	Function of binary input 1 None NO Only signal Block configuring Block config. and manual Drive valve to up position Drive valve to down position Block movement NC Only signal Drive valve to up position Drive valve to down position Block movement	OFF  on bLoc1 bLoc2 uP doWn StoP  -on -uP -doWn -Stop	
43. BIN2 <sup>4)</sup>	Function of binary input 2 None NO Only signal Drive valve to up position Drive valve to down position Block movement NC Only signal Drive valve to up position Drive valve to down position Block movement	OFF  on uP doWn StoP  -on -uP -doWn -StoP	
44. AFCT <sup>5)</sup>	Alarm function None A1=min,A2=max: normal inverted A1=min,A2=min: normal inverted A1=max,A2=max: normal inverted	oFF Mi:MA Mi:MA Mi:Mi Mi:Mi MA:MA MA:MA	
45. A1	Response threshold for alarm 1	0.0 to 100.0	%
46. A2	Response threshold for alarm 2	0.0 to 100.0	%
47. fFCT <sup>5)</sup>	Function of alarm output Fault: normal inverted Fault + not Automatic: normal inverted Fault + not Automatic + BI: normal inverted (+ means logical OR operation)	f -f  f nA -f nA  f nA.b -f nA.b	
48. fTIM	Monitoring time for setting of fault signal "Control deviation"	Auto 0 to 100	s
49. fLIM	Response threshold of fault signal "Control deviation"	Auto 0.0 to 100.0	%
50. fSTRK	Limit for travel integral	OFF 1 to 1.00E9	
51. fDCHG	Limit for change in direction	OFF 1 to 1.00E9	
52. fZERO	Limit for zero limit monitoring	OFF 0 to 100.0	%
53. fOPEN	Limit for open limit monitoring	OFF 0 to 100.0	%
54. fDEBA	Limit for dead zone monitoring	OFF 0 to 100.0	%
55. PRST	Preset - Nothing activated - Start of factory settings - Display after pressing key for 5 s	no Strt  oCAY	

# SIPART PS2 electropneumatic positioners

## SIPART PS2, SIPART PS2 PA, SIPART PS2 EEx d and SIPART PS2 EEx d PA

### Configuring

#### SIPART PS2 and SIPART PS2 EEx d PA configurations (PROFIBUS versions)

Parameter name	Function	Parameter values	Dimension
1. YFCT	Type of actuator: part-turn/linear - Part-turn actuator - Linear actuator - Linear actuator without sine-wave correction	turn WAY LWAY	
2. YAGL <sup>1)</sup>	Rated angle of feedback	90 ° 33 °	De-grees
3. YWAY <sup>2)</sup>	Travel range 5 to 130 mm - None - Short lever 33° - Short lever 90° - Long lever 90°	OFF 5/10/15/20 25/30/35 40/50/60/70/90/ 110/130	mm
4. INIT	Initialization (automatic commissioning)	no Strt run 1 to run 5 ##.# or oFF	
5. SDIR	Setpoint direction rising Setpoint direction falling	riSE FALL	
6. TSI	Setpoint ramp OPEN	AUto 0 to 400	s
7. TSD	Setpoint ramp CLOSED	AUto 0 to 400	s
8. SFCT	Setpoint function - Linear - Equal percentage - Equal percentage, reversed - Freely adjustable	Lin 1:25, 1:33, 1:50 1:25, 1:33, 1:50 FrEE	
9. SLO <sup>3)</sup>	Setpoint interpolation points with free characteristic	0.0 to 100.0	%
29. SL20	0 %, 5 %, 10 % ... 100 %		
30. DEBA	Controller dead zone	AUto 0.1 to 10.0	%
31. YA	Start of manipulated variable limit	0.0 to 100.0	%
32. YE	End of manipulated variable limit	0.0 to 100.0	%
33. YNRM	Manipulated variable scaling mech. travel/flow	MPoS FLoW	
34. YCLS	"Tight shut-off" with man. variable	no uP: :dW uP:dW	
35. YCDO	Value for "tight shut-off", down	0.0 to 100.0	%
36. YCUP	Value for "tight shut-off", up	0.0 to 100.0	%
37. BIN1 <sup>4)</sup>	Function of binary input 1 None NO Only signal Block configuring Block config. and manual Drive valve to ye Drive valve to ya Block movement NC Only signal Drive valve to ye Drive valve to ya Block movement	OFF on bLc1 bLc2 uP doW StoP -on -uP -doW -Stop	

Parameter name	Function	Parameter values	Dimension
38. BIN2 <sup>4)</sup>	Function of binary input 2 None NO Only signal Drive valve to ye Drive valve to ya Block movement NC Only signal Drive valve to ye Drive valve to ya Block movement	OFF on uP doW StoP -on -uP -doW -StoP	
39. AFCT	Alarm function None min : max: normal inverted min : min: normal inverted max : max: normal inverted	oFF Mi:MA Mi:MA Mi:Mi Mi:Mi MA:MA MA:MA	
40. A1	Response threshold for alarm 1	0.0 to 100.0	%
41. A2	Response threshold for alarm 2	0.0 to 100.0	%
42. lFCT <sup>5)</sup>	Function of alarm output Fault: normal inverted Fault + not Automatic: normal inverted Fault + not Automatic + BI: normal inverted (+ means logical OR operation)	l -l l nA -l nA l nA.b -l nA.b	
43. lTIM	Monitoring time for setting of fault signal "Control deviation"	Auto 0 to 100	s
44. lLIM	Response threshold of fault signal "Control deviation"	Auto 0.0 to 100.0	%
45. PRST	Preset (factory setting)	no Strt oCAY	
46. FSTY	Safety setting: Parameterized safety setpoint Last setpoint Open exhaust air valve	FSVL FSSP FSAC	
47. FSTI	Monitoring time for setting of safety position	0 to 100	s
48. FSVL	Safety setpoint	0 to 100.0	%
49. STNR	Station number	0 to 126	

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## SIPART PS2, SIPART PS2 PA, SIPART PS2 EEx d and SIPART PS2 EEx d PA

### Technical data

#### Technical data

**SIPART PS2**  
**SIPART PS2 EEx d**  
**SIPART PS2 PA**  
**SIPART PS2 EEx d PA**

#### General data

Travel range (linear actuators)	3 to 130 mm (angle of feedback shaft 16 to 90°)
Angle or rotation (part-turn actuators)	30 to 100°
Installation	
• On linear actuators	Using mounting kit 6DR4004-8V and additional lever arm 6DR4004-8L if required on actuators according to IEC 534-6 (NAMUR) with ledge, columns or plane surface
• On part-turn actuators	Using mounting kit 6DR4004-8D on actuators with fixing platform according to VDI/VDE 3845 and DIN 3337: the mounting plate must be provided on the actuator side; shaft with nut and M6 female thread (see Fig. 5/15)

#### Controller

• Five-point switch	Self-adjusting
• Dead zone	Self-adjusting or fixed setting
• dEbA = Auto	
• dEbA = 0.1 to 10%	
• Controllable response time	≥ 1.5 s, reduced resolution with smaller positioning times

#### A/D converter

• Scanning time	10 ms
• Resolution	≤ 0.05 %
• Transmission error	≤ 0.2 %
• Temperature influence	≤ 0.1 %/10 K

Binary input BI1 (connected electrically to  $I_w$  current input)  
 Contact rating

Degree of protection IP 65 to EN 60 529

#### Mounting position

Any; in wet environment, pneumatic connections and exhaust opening not upwards

#### CE marking

Conforms to EMC guideline 89/336 EEC in compliance with the following standards

• Emitted interference	EN 50 081-1
• Noise immunity	EN 50 082-2 and NAMUR NE21 May 93

#### Material of:

• Casing	
- 6DR5 0-... (plastic)	Glass-fiber-reinforced Macrolon
- 6DR5 1-... (metal)	GK-AISI7Mg
- 6DR4 5-... (metal)	GK-AISI7Mg

• Pressure gauge block Aluminium AlMgSi, anodized

Resistance to vibration 10 g

#### Pneumatic data

Supply (inlet air)

- Pressure

1.4 to 7 bar: sufficiently larger than max. actuator pressure (positioning pressure)

Air quality according to ISO 8573-1

- Size and density of particulates
- Pressure dew point

Class 2

Class 2 (min. 20 K below ambient temperature)

Class 2

Unrestricted flow of:

- Inlet air valve [Nm<sup>3</sup>/h]
- Outlet air valve [Nm<sup>3</sup>/h]

At	2 bar	4 bar	6 bar
	4.1	7.1	9.8
	8.2	13.7	19.2

Valve leakage

< 6 × 10<sup>-4</sup> Nm<sup>3</sup>/h

Throttle ratio

Adjustable up to ∞ : 1

Consumption of inlet air in stable state

< 3.6 × 10<sup>-2</sup> Nm<sup>3</sup>/h

Types of actuators

- In plastic casing
- In metal casing
- In flameproof casing

Single-action and double-action

Single-action

Single-action and double-action

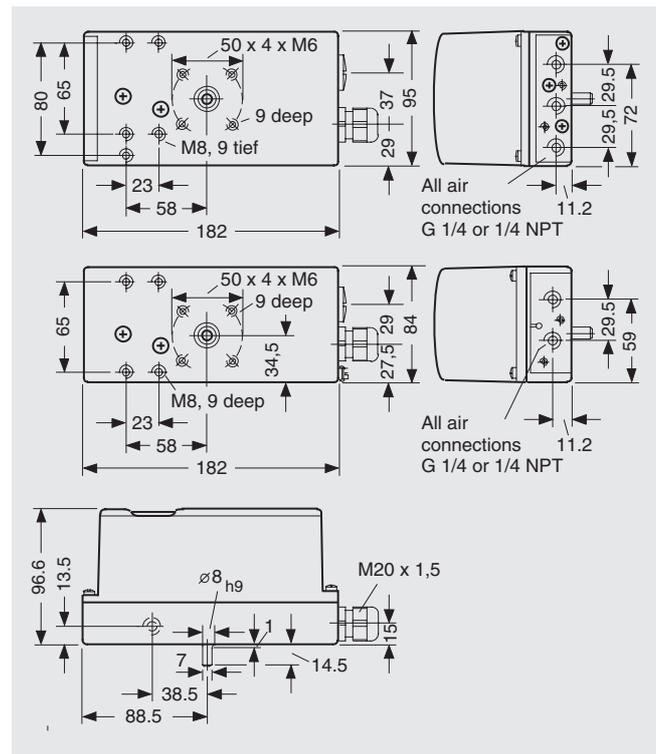


Fig. 5/13 Dimensions (top: plastic casing, center: metal casing, bottom: plastic casing and metal casing)

# SIPART PS2 electropneumatic positioners

## SIPART PS2, SIPART PS2 PA, SIPART PS2 EEx d and SIPART PS2 EEx d PA

### Technical data

Technical data		
<b>SIPART PS2</b>		
Explosion protection to EN 50 014 and EN 50 020	EEx n II 3G Ex nV II T4	EEx ia/ib II G EEx ib II C T6
Mounting location	Zone 2	Zone 1
Permissible ambient temperature for operation	T4: -30 to +80 °C <sup>1)</sup>	T4: -30 to +80 °C <sup>1)</sup> T5: -30 to +65 °C <sup>1)</sup> T6: -30 to +50 °C <sup>1)</sup>
<b>Electrical data</b>		
	<b>Basic device without Ex protection</b>	<b>Basic device with Ex protection EEx ia/ib or Ex n</b>
Input		
<u>Two-wire system</u>		
• Rated signal range		4 to 20 mA
• Current to maintain power supply		≥ 3.6 mA
• Required load voltage $U_B$ (≅ Ω at 20 mA)		
- Without HART	6.4 V (≅ 320 Ω)	8.0 V (≅ 400 Ω)
- With HART	6.5 V (≅ 325 Ω)	8.8 V (≅ 440 Ω)
• Static destruction limit	± 40 mA	-
• Internal capacitance $C_i$	-	≤ 15 nF
• Internal inductance $L_i$	-	≤ 0.12 mH
• Sources	-	Intrinsically-safe with $U_o \leq 30$ V DC $I_k \leq 100$ mA $P \leq 1$ W
<u>Three-wire/four-wire system (only 6DR52...)</u>		
• Power supply $U_H$		18 to 30 V DC
• Current consumption $I_H$		$(U_H - 7.5 \text{ V})/2.4 \text{ k}\Omega$ [mA]
• Internal capacitance $C_i$	-	≤ 15 nF
• Internal inductance $L_i$	-	≤ 0.12 mH
• For connection to intrinsically-safe sources with	-	$U_o \leq 30$ V DC $I_k \leq 100$ mA $P \leq 1$ W
Current input $i_W$		
• Rated signal range		0/4 to 20 mA
• Load voltage at 20 mA		1 V (≅ 50 Ω)
• Internal capacitance $C_i$	-	≤ 15 nF
• Internal inductance $L_i$	-	≤ 0.12 mH
• For connection to intrinsically-safe sources with	-	$U_o \leq 30$ V DC $I_k \leq 100$ mA $P \leq 1$ W
Electrical isolation		Between $U_H$ and $I_W$ (2 intrinsically-safe circuits)
• Test voltage		840 V DC (1 s)
Connections		
• Electric		Screw terminals 2.5 AWG28-12 Cable bushing M20 or 1/2" NPT (see Ordering data)
• Pneumatic		Female thread G1/4 DIN 45 141 or 1/4" 18 NPT (see Ordering data)

Binary input BI1	See "General data", page 5/10
Weight, basic device	
• Plastic casing	Approx. 0.9 kg
• Metal casing	Approx. 1.3 kg
Dimensions	See Fig. 5/13
Climatic class	To IEC 721
• Storage	1K5, but -40 to +80 °C <sup>2)</sup>
• Transport	2K4, but -40 to +80 °C <sup>2)</sup>
• Operation	
- Without purging air	3K3, but -30 to +80 °C <sup>1)</sup>
- With purging air	3K4, but -30 to +80 °C <sup>1)</sup>
<b>SIPART PS2 EEx d</b>	
Explosion protection to EN 50 014 and EN 50 018	II 2G EEx d II C T6
Permissible ambient temperature for operation	T4: -30 to +80 °C <sup>1)</sup> T5: -30 to +65 °C <sup>1)</sup> T6: -30 to +50 °C <sup>1)</sup>
<b>Electrical data</b>	
Input	
<u>Two-wire system</u>	
• Rated signal range	4 to 20 mA
• Current to maintain power supply	≥ 3.6 mA
• Required load voltage $U_B$	
- Without HART	6.4 V (≅ 320 Ω)
- With HART	6.5 V (≅ 325 Ω)
• Static destruction limit	± 40 mA
<u>Three/four-wire system</u>	
• Power supply $U_H$	18 to 35 V DC
• Current consumption $I_H$	$(U_H - 7.5 \text{ V})/2.4 \text{ k}\Omega$ [mA]
• Static destruction limit	± 35 V
Current input $i_W$	
• Rated signal range	0 or 4 to 20 mA
• Load voltage at 20 mA	1 V (≅ 50 Ω)
• Static destruction limit	± 40 mA
Electrical isolation	Between $U_H$ and $I_W$
• Test voltage	500 V (50 Hz, 1 min)
Connection	Screw terminals 2.5 AWG28-12
• Electric	1/2" NPT <sup>3)</sup> or M25 x 1.5 <sup>3)</sup> or M20 x 1.5
• Pneumatic	Female thread G1/4 DIN 45 141 or 1/4" 18NPT
Binary input BI1	See "General data", page 5/10
Weight, basic device	Approx. 5.2 kg
Dimensions	See Fig. 5/14
Climatic class	To IEC 721
• Storage	1K5, but -40 to +80 °C <sup>2)</sup>
• Transport	2K4, but -40 to +80 °C <sup>2)</sup>
• Operation with purging air	3K4, but -30 to +80 °C <sup>2)</sup>

<sup>1)</sup> Limited refresh rate of LCD below -10 °C.

<sup>2)</sup> When commissioning at ≤ 0 °C make sure that the valves are purged with the dry medium for a sufficiently long time.

<sup>3)</sup> With EEx-d certified cable bushing.

# SIPART PS2 electropneumatic positioners

## SIPART PS2, SIPART PS2 PA, SIPART PS2 EEx d and SIPART PS2 EEx d PA

### Technical data

#### Technical data (continued)

##### SIPART PS2 PA

Explosion protection to EN 50 014 and EN 50 020  
Permissible ambient temperature

##### Electrical data

	Basic device without Ex protection	Basic device with Ex protection EEx ia
Explosion protection to EN 50 014 and EN 50 020		EEx ia IIC T4/T5/T6
Permissible ambient temperature	–	T4: -30 to +80 °C T5: -30 to +65 °C T6: -30 to +50 °C
<b>Electrical data</b>		
Power supply		Via bus
Bus voltage	9 to 32 V	9 to 24 V
Current consumption		12 mA ± 10 %
Electronic current limiting		$I_{max} = \leq 16$ mA in event fault
Effective internal inductance	–	$L_i \leq 7.2$ mH
Effective internal capacitance	–	$C_i \leq 550$ pF
Connection	–	Certified intrinsically-safe circuit
Supply unit		$U_p = 24$ V; $I_p = 128$ mA
Electrical isolation	Between bus and secondary circuit	Between bus and secondary circuit (2 intrinsically-safe circuits)
Test voltage (50 Hz, 1 min)	–	500 V <sub>rms</sub>
Communication		Layers 1 + 2 according to PROFIBUS-PA, transmission system to IEC 1158-2; slave function Layer 7 (protocol layer) according to PROFIBUS-DP, standard EN 50 170 with extended PROFIBUS functionality (all data acyclic; manipulated variable, feedbacks and status cyclic in addition)
C2 connections		Four connections to master class 2 are supported, automatic establishment of connection 60 s following interruption in communication
Device profile		PROFIBUS-PA profile B, version 3.0; more than 150 objects
Response time to master telegram		Typ. 10 ms
Device address		126 (when delivered)
PC parameterization software		SIMATIC PDM, executes on Windows 95 or Windows NT; supports all device objects The software is not included in the scope of delivery
Connections		
• Electric		Screw terminals 1.5 AWG14 Cable bushing M20 (1/2" NPT, see Ordering data)
• Pneumatic		Female thread G1/4 DIN 45 141 (1/4" NPT, see Ordering data)
Binary input BI1		See "General data", page 5/10
Weight, basic device		
• Plastic casing		Approx. 0.9 kg
• Metal casing		Approx. 1.3 kg

Dimensions	See Fig. 5/13
Climatic class	To IEC 721
• Storage	1K5, but -40 to +80 °C <sup>1)</sup>
• Transport	2K4, but -40 to +80 °C <sup>1)</sup>
• Operation	
- Without purging air	3K3, but -30 to +80 °C <sup>2)</sup>
- With purging air	3K4, but -30 to +80 °C <sup>2)</sup>
<b>SIPART PS2 EEx d PA</b>	
Explosion protection to EN 50 014 and EN 50 018	II 2G EEx d IIC T6
Permissible ambient temperature for operation	T4: -30 to +80 °C <sup>2)</sup> T5: -30 to +65 °C <sup>2)</sup> T6: -30 to +50 °C <sup>2)</sup>
<b>Electrical data</b>	
Power supply	Via bus
Bus voltage	9 to 32 V
Current consumption	12 mA ± 10 %
Electronic current limiting	$I_{max} = \leq 16$ mA in event of fault
Supply unit	$U_p = 24$ V; $I_p = 128$ mA
Electrical isolation	Between bus and secondary circuit
Test voltage (50 Hz, 1 min)	500 V <sub>rms</sub>
Communication	Layers 1 + 2 according to PROFIBUS-PA, transmission system to IEC 1158-2; slave function Layer 7 (protocol layer) according to PROFIBUS-DP, standard EN 50 170 with extended PROFIBUS functionality (all data acyclic; manipulated variable feedbacks and status cyclic in addition)
C2 connections	Four connections to master class 2 are supported, automatic establishment of connection 60 s following interruption in communication
Device profile	PROFIBUS-PA profile B, version 3.0; more than 150 objects
Response time to master telegram	Typ. 10 ms
Device address	126 (when delivered)
PC parameterization software	SIMATIC PDM, executes on Windows 95 or Windows NT; supports all device objects The software is not included in the scope of delivery
Connections	
• Electric	Screw terminals 1.5 AWG14 EEx d certified cable bushing
• Pneumatic	Female thread G1/4 DIN 45 141 1/4" 18NPT
Binary input BI1	See "General data", page 5/10
Weight, basic device	Approx. 5.2 kg
Dimensions	See Fig. 5/14
Climatic class	To IEC 721
• Storage	1K5, but -40 to +80 °C <sup>1)</sup>
• Transport	2K4, but -40 to +80 °C <sup>1)</sup>
• Operation	3K4, but -30 to +80 °C <sup>2)</sup>

1) When commissioning at  $\leq 0$  °C make sure that the valves are purged with the dry medium for a sufficiently long time.

2) Limited refresh rate of LCD below -10 °C.

# SIPART PS2 electropneumatic positioners

## SIPART PS2, SIPART PS2 PA, SIPART PS2 EEx d and SIPART PS2 EEx d PA

### Technical data

#### Technical data (continued)

Option modules	Without Ex protection	With Ex protection
<b>Electrical data</b>		
Explosion protection to EN 50 014 and EN 50 020	–	II2G EEx ia/ib II C T4/T5/T6 <sup>1)</sup>
Mounting location	–	Zone 1
Permissible ambient temperature for operation	-30 to +80 °C	T4: -30 to +80 °C T5: -30 to +65 °C T6: -30 to +50 °C
<b>Alarm module</b>	6DR4004-8A (without Ex protection)	6DR4004-6A (with Ex protection)
<b>Binary alarm outputs <math>\overline{A1}</math>, <math>\overline{A2}</math> and alarm output</b>		
Signal status High (not triggered)	Conductive $R = 1 \text{ k}\Omega$ , +3/-1 %	$\geq 2.1 \text{ mA}^2$
Signal status Low <sup>3)</sup> (triggered)	Non-conductive $I_R < 60 \mu\text{A}$	$\leq 1.2 \text{ mA}^2$
Internal capacitance $C_i$	–	$\leq 5.2 \text{ nF}$
Internal inductance $L_i$	–	Negligible
Power supply $U_H$	$\leq 35 \text{ V}$	–
Connection to intrinsically-safe switching amplifier to DIN 19 234	–	$U_o \leq 15.5 \text{ V DC}$ $I_k \leq 25 \text{ mA}$ $P \leq 64 \text{ mW}$
<b>Binary input BI2</b>		
• Electrically connected to basic device		Floating contact, open Floating contact, closed 3 V, 5 $\mu\text{A}$
- Signal status 0		
- Signal status 1		
- Contact rating		
• Electrically isolated from basic device		$\leq 4.5 \text{ V}$ or open $\geq 13 \text{ V}$ $\geq 25 \text{ k}\Omega$
- Signal status 0		
- Signal status 1		
- Input resistance		
Static destruction limit	$\pm 35 \text{ V}$	–
Internal inductance and capacit.	–	Negligible
Connection to intrinsically-safe voltage source	–	$U_i \leq 25.2 \text{ V}$
Electrical isolation		The 3 outputs, the input BI2 and the basic device are electrically isolated from each other
<b>I<sub>y</sub> module</b>	6DR4004-8J (w/o Ex protection)	6DR4004-6J (with Ex protection, only for temp. class T1 to T4)
<b>Direct current output for position feedback</b>		Two-wire system
Rated signal range $i$		4 to 20 mA, short-circuit-proof
Operating range		3.6 to 20.5 mA
Power supply $U_H$	+12 to 35 V	+12 to 30 V
External load $R_B$ [k $\Omega$ ]		$\leq (U_H [\text{V}] - 12 \text{ V}) / i [\text{mA}]$
Transmission error		$\leq 0.3 \%$
Temperature influence		$\leq 0.1 \%$ /10 K
Resolution		$\leq 0.1 \%$
Residual ripple		$\leq 1 \%$
Internal capacitance $C_i$	–	$\leq 11 \text{ nF}$
Internal inductance $L_i$	–	Negligible
For connection to intrinsically-safe sources with		for T4
• $U_i$	–	$\leq 30 \text{ V}$
• $I_i$	–	$\leq 100 \text{ mA}$
• $P_i$	–	$\leq 1 \text{ W}$

#### SIA module

Limit monitor with slot-type initiators and alarm output	6DR4004-8G or 6DR4004-6G (only for 6DR5...)
Connection	Two-wire system to DIN 19 234 (NAMUR), for series-connected switching amplifiers
2 slot-type initiators	Type SJ2-SN
Function	NC
Connection to intrinsically-safe switching amplifier, DIN 19 234	
Ex protection	EEx ia/ib IIC T4/T5/T6
EMC	Acc. to EN 60 947-5-2 and DIN 19 234
Alarm output	See alarm module

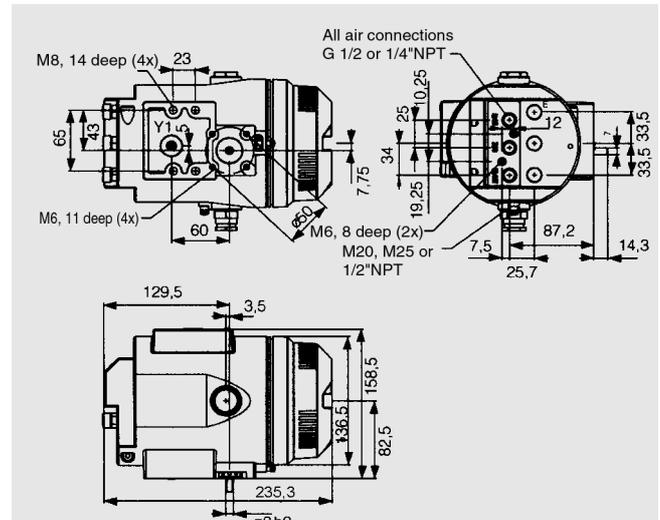


Fig. 5/14 Dimensional drawing of flameproof casing

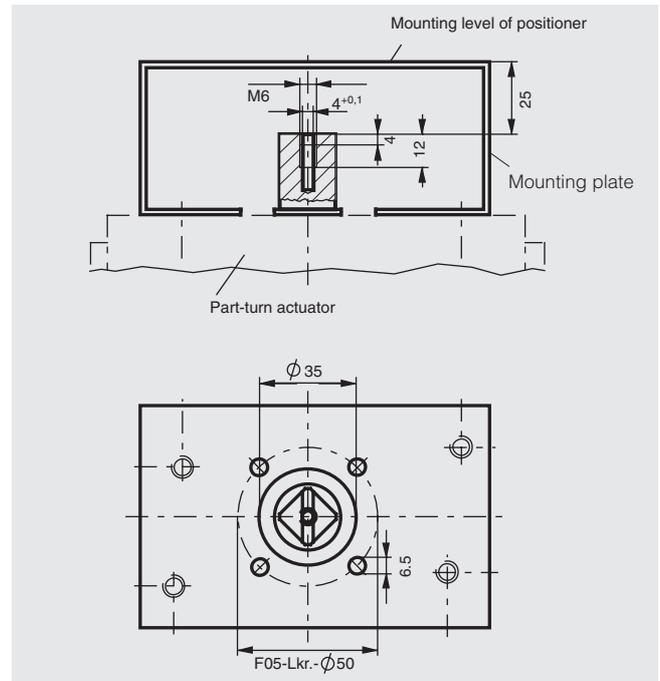


Fig. 5/15 Mounting onto part-turn actuators; mounting plate (scope of delivery of actuator manufacturer), extract from VDI/VDE 3845, dimensions

<sup>1)</sup> Only in conjunction with the basic device 6DR5 ■■■■ - ■ E ■■■■.  
<sup>2)</sup> Switching thresholds with supply to DIN 19 234:  $U_H = 8.2 \text{ V}$ ,  $R_i = 1 \text{ k}\Omega$ .  
<sup>3)</sup> Low is also the state if the basic device is faulty or without an electrical power supply.



# SIPART PS2 electropneumatic positioners

## SIPART PS2, SIPART PS2 PA, SIPART PS2 EEx d and SIPART PS2 EEx d PA

### Ordering data

Ordering data	Order No.
<b>Accessories</b>	
<b>Alarm module</b> for 3 alarm outputs and 1 binary input (functions: 2 limit monitors, 1 fault indication, 1 binary input)	
- Without explosion protection	<b>6DR4004-8A</b>
- With explosion protection CENELEC	<b>6DR4004-6A</b>
- With explosion protection FM <sup>1)</sup>	<b>6DR4004-7A</b>
<b>SIA module</b> (slot initiator alarm module, not for 6DR4...)	
- Without explosion protection	<b>6DR4004-8G</b>
- With explosion protection CENELEC and FM	<b>6DR4004-6G</b>
<b>I<sub>v</sub> module</b> for position transmitter signal (4 to 20 mA)	
- Without explosion protection	<b>6DR4004-8J</b>
- With explosion protection CENELEC	<b>6DR4004-6J</b>
- With explosion protection FM <sup>1)</sup>	<b>6DR4004-7J</b>
<b>HART module</b> (for 6DR400 - - -)	
- Without explosion protection	<b>6DR4004-8H</b>
- With explosion protection CENELEC	<b>6DR4004-6H</b>
- With explosion protection FM <sup>1)</sup>	<b>6DR4004-7H</b>
<b>HART communicator</b> With battery, charger for AC 230 V and bag, type of protection "Intrinsic safety" EEx ia II T4	
• German	<b>7MF4998-8KF</b>
• English	<b>7MF4998-8KT</b>
<b>HART modem</b> for connection to PC or laptop for 6DR40... and 6DR5...	<b>7MF4997-1DA</b>
<b>Mounting kit</b> Mounting of positioner on:	
• Linear actuator up to 35 mm travel	<b>6DR4004-8V</b>
• Part-turn actuator	<b>6DR4004-8D</b>
• SAMSON actuator, type 3277, yoke dimension H5 = 101 mm <sup>2)</sup> (integrated mounting without pipe)	<b>6DR4004-8S</b>
<b>Lever arm</b> for travels from 35 to 130 mm	<b>6DR4004-8L</b>
<b>Reduced mounting set</b> for linear actuator (without bracket and U-bolt)	
• With short lever up to 35 mm travel	<b>6DR4004-8VK</b>
• With long lever > 35 mm travel	<b>6DR4004-8VL</b>
<b>Pressure gauge block</b> including pressure gauges	
• For single-action SIPART PS2 positioner (2 pressure gauges)	<b>6DR4004-1M</b>
• For double-action SIPART PS2 positioner (3 pressure gauges)	<b>6DR4004-2M</b>

Ordering data	Order No.
<b>Accessories (continued)</b>	
<b>Connection block</b> for safety solenoid valve with extended mounting flange to NAMUR	
• For mounting according to IEC 534-6	<b>6DR4004-1B</b>
• For SAMSON actuator (integrated mounting), see above	<b>6DR4004-1C</b>
<b>Set of rating plates Ex n</b> (for 6DR400 - - E) for conversion to Ex n mode approval (zone 2)	<b>C73451-A430-D55</b>
<b>External position detection system</b> (for non-explosion-proof applications) for separate mounting of position sensor and controller, comprising:	<b>C73451-A430-D78</b>
• SIPART PS2 plastic casing with integral potentiometer and sliding clutch (without electronics and valve block)	
• EMC filter module for controller (required for CE marking; separate ordering item), see below	
<b>NCS sensor</b> for non-contacting detection of position non explosion-proof explosion-proof Mounting NAMUR for part-turn actuators for linear actuators up to 16 mm for linear actuators > 16 mm Assembly and Installation Instructions	<b>6DR4004 - - N - - -</b>
• German/English	
• French/Italian/Spanish	
<b>EMC filter module</b> for connection of external position sensor (10 kΩ)	<b>C73451-A430-D23</b>
<b>Documentation</b> Assembly and Installation Instructions	
• German/English	<b>A5E00074600</b>
• French/Italian/Spanish	<b>A5E00074601</b>
Manual	
• German	<b>A5E00074630</b>
• English	<b>A5E00074631</b>
<b>SITRANS I output isolating HART</b> (see Part 6) with	
• 24 V AC/DC power supply	<b>7NG4130-1AA11</b>
• 230 V AC power supply	<b>7NG4130-1BA11</b>

Available ex-stock.

<sup>1)</sup> U.S. certification by FM institute.

<sup>2)</sup> With a yoke dimension H5 = 95 mm, only the SIPART PS2 in metal casing can be used.

# SIPART PS2 electropneumatic positioners

SIPART PS2, SIPART PS2 PA, SIPART PS2 EEx d and SIPART PS2 EEx d PA

## Ordering data

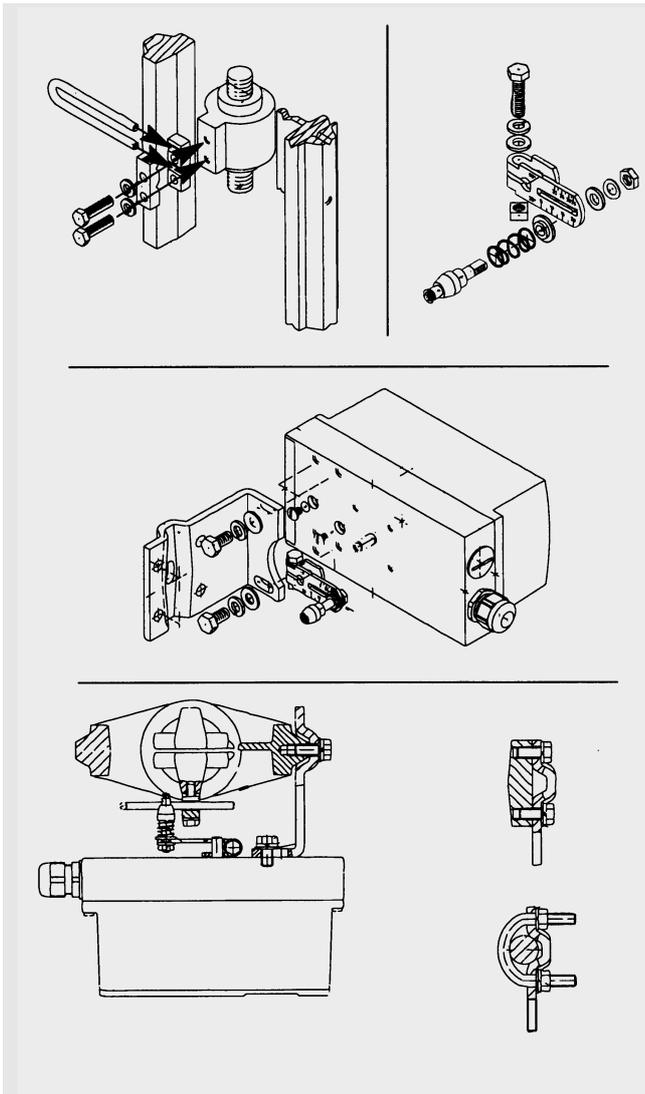


Fig. 5/16 Mounting of SIPART PS2 (PA) on linear actuators

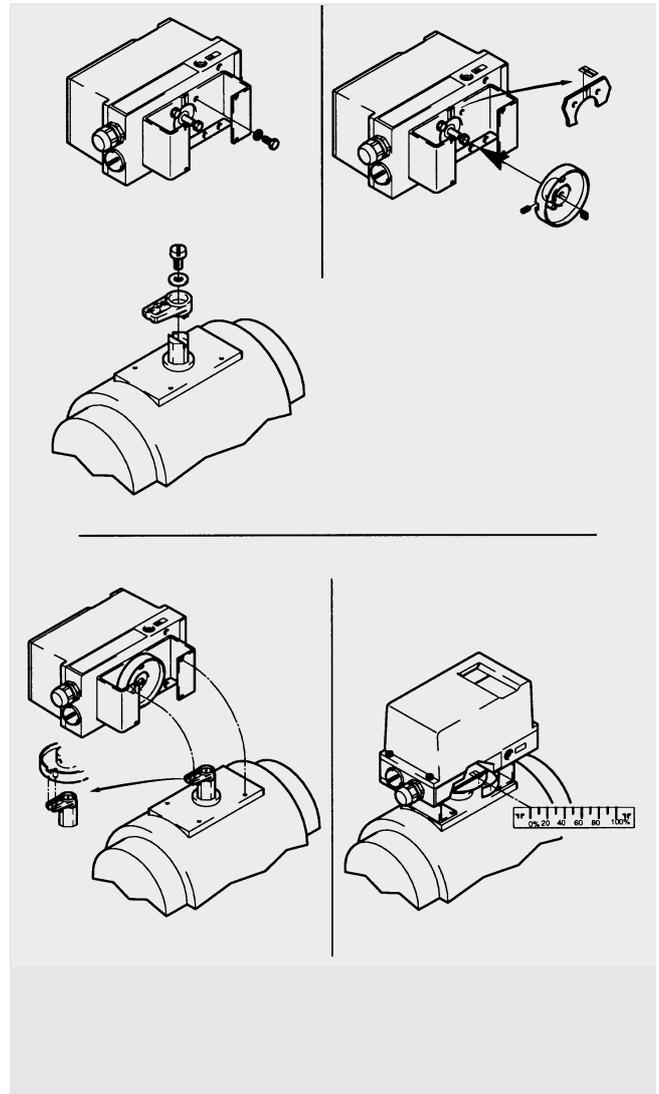


Fig. 5/17 Mounting of SIPART PS2 (PA) on part-turn actuators

# SIPART PS2 electropneumatic positioners

## SIPART PS2, SIPART PS2 PA, SIPART PS2 EEx d and SIPART PS2 EEx d PA

### Ordering data

#### Ordering data

##### Scope of delivery for positioner

Scope of delivery includes:

- 1 SIPART PS2 positioner as ordered
- 1 Assembly and Installation Instructions (German/English) according to device type
- 1 each SIPART PS2 Configuring Instructions - a concise overview in German and English

##### Scope of delivery for mounting kit 6DR4004-8V (for linear actuators)

- 1 Mounting bracket
- 2 Mounting prisms
- 1 U-bracket
- 1 Lever arm with adjustable pick-up roll
- 2 U-bolts

Various screws and lock washers

##### Scope of delivery for mounting kit 6DR4004-8D (for part-turn actuators)

- 1 Coupling wheel
- 1 Driver pin
- 8 Scales
- 1 Pointer

Various screws and lock washers

Caution:

The mounting consoles and the screws for mounting onto the part-turn actuator are not included in the scope of delivery and must be provided by the customer (see Technical data).

##### Available ex-stock

Items marked  are available ex-stock.

##### Training

Refer to Catalog ITC for details of training courses for these devices.

##### Special designs on request

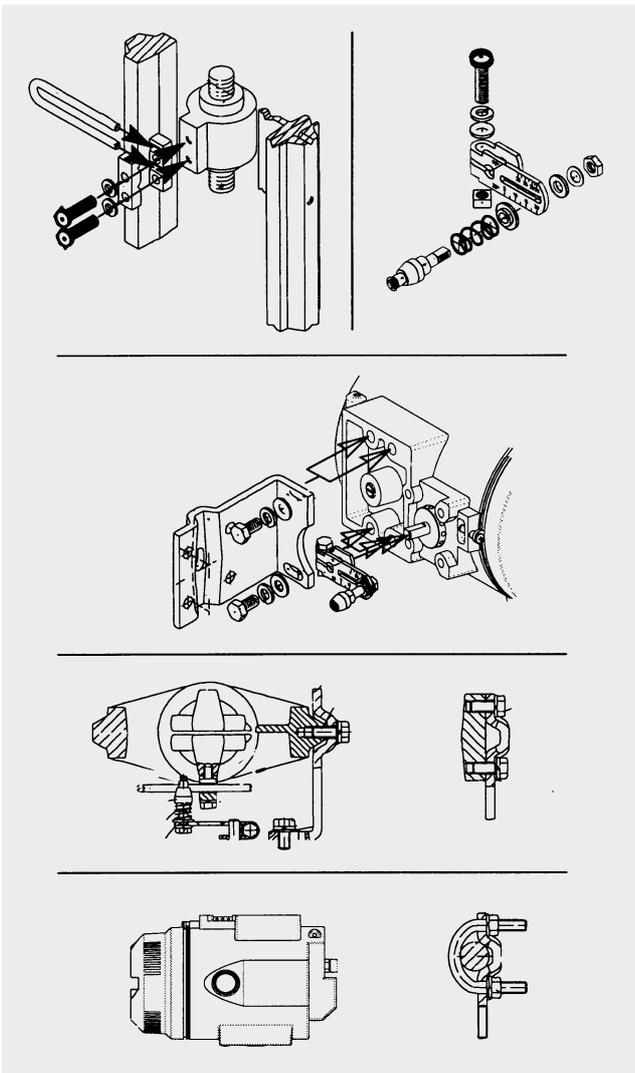


Fig. 5/18 Mounting of SIPART PS2 EEx d (PA) on linear actuators

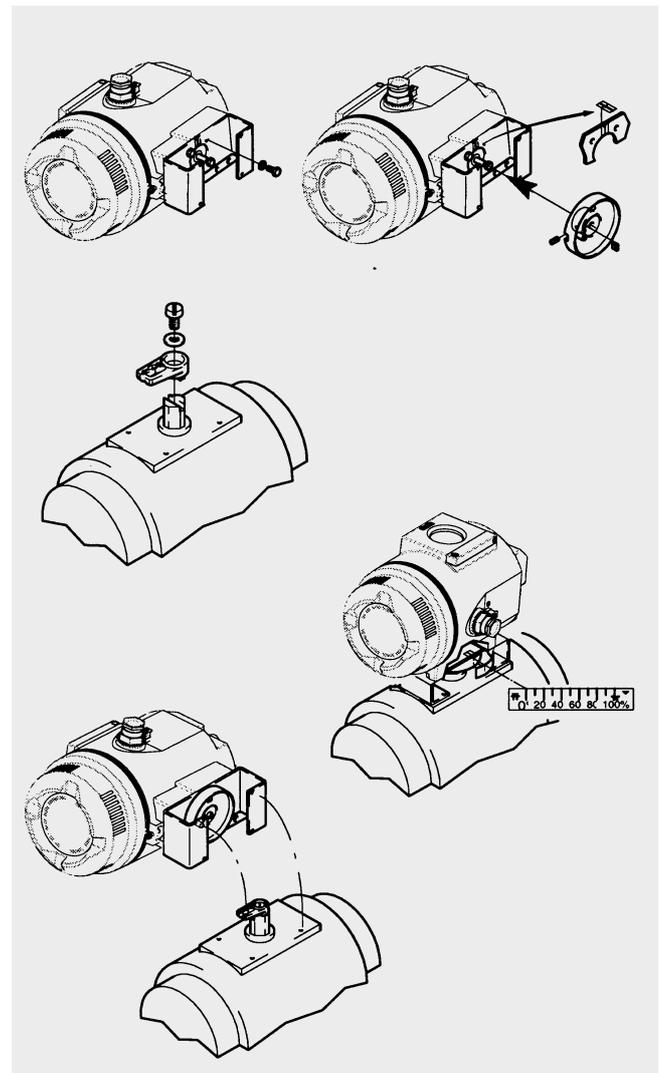


Fig. 5/19 Mounting of SIPART PS2 EEx d (PA) on part-turn actuators