# Pneumatic Positioner Type 3766 Electropneumatic Positioner Type 3767



#### Application

Single-acting or double-acting positioners for attachment to pneumatic control valves. Supplied with standardized pneumatic signal 0.2 to 1 bar or 3 to 15 psi (Type 3766) or a standardized electric signal from 4 (0) to 20 mA or 1 to 5 mA (Type 3767).

Rated travels from 7.5 to 120 mm or opening angle up to 90°



Conversion of valve sizing coefficients:  $C_v$  (in U.S. gallons/min) = 1.17 · K<sub>vs</sub> (in m<sup>3</sup>/h)  $K_{vs}$  (in m<sup>3</sup>/h) = 0.86 · C<sub>v</sub> (in U.S. gallons/min)

The positioners ensure a preselected correspondence between the valve stem position (controlled variable x) and the pneumatic or electric input signal supplied by the controller (reference variable w). They compare the reference input signal received from the control device to the travel of the control valve and, depending on the comparison, produce the corresponding pneumatic output signal pressure  $p_{st}$  (output variable y). The output from the positioner is the input signal to the actuator. A reversing amplifier (booster) in the double-acting actuators produces two opposed signal pressures.

#### Special features include:

 Compact design requiring very little maintenance; arbitrary mounting position; very insensitive to mechanical vibrations; excellent dynamic response; suitable for normal or splitrange operation; adjustable proportional band (P-band); adjustable air output capacity; low supply consumption; negligibly small supply influence.

Versions for hazardous areas are available in Type of Protection "Intrinsic Safety" <sup>(G)</sup> II 2 G EEx ia IIC T6 or <sup>(G)</sup> II 3 G EEx nA II T6 for Zone 2 (see "Summary of the explosion protection certifications" on page 8). Type of Protection "Flameproof Enclosure" EEx d with Type 3766 Positioner and Type 6116 i/p Converter (Fig. 2).

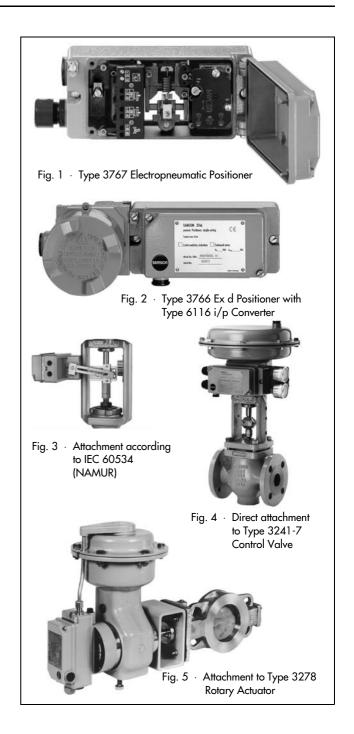
Special version with case made of CrNiMo steel available. Direct attachment to Type 3277 Pneumatic Actuator (Fig. 4). Attachment to actuators according to IEC 60534-6 (Fig. 3). Attachment to rotary actuators according to VDI/VDE 3845 (Fig. 5); double-acting actuators have a reversing amplifier.

#### Benefits of direct positioner attachment (Fig. 4)

- Tight and exact mechanical connection between actuator and positioner. No false adjustment during shipping.
- Concealed linkage protected against touch and external influences; therefore, the requirements of the accident prevention regulations UVV (VBG 5) are met.
- Simple pneumatic connection between actuator and positioner
- Presetting of the unit: "Actuator with attached positioner"

Optional pressure gauge for monitoring the input and output signal pressure (scale 0 to 6 bar and 0 to 90 psi).

See Information Sheet T 8350 EN for details on the selection and application of positioners, converters, limit switches and solenoid valves.



Associated Information Sheet

Edition August 2004

Data Sheet

#### Principle of operation (Figs. 6 to 8)

The only difference between the Type 3766 Pneumatic Positioner (Fig. 6) and the Type 3767 Electropheumatic Positioner (Fig. 7) is that an electropneumatic (i/p) converter (E) has been added to the latter in order to convert the electric signal received from a controller into a proportional pneumatic signal.

With the Type 3767 Electropneumatic Positioner (Fig. 7), the dc current signal (i), which is received from a control device, flows through the plunger coil (E2) in the field of a permanent magnet (E1). On the balance beam (E3), the force, which is proportional to the dc current i, is balanced against the force of the back-pressure which is generated on the flapper plate (E7) by the jet stream leaving the nozzle (E6). Any changes of the current signal proportionally vary the input pressure pe supplied to the pneumatic control system.

With linear-motion valves, the travel and therefore the valve stem position is transmitted to the follower lever (1) via the pin (1.1) and determines the force of the measuring spring (4). When the positioner is attached to rotary-motion valves (Fig. 8), a follower roll (20) is attached to the front end of the lever (1). The rotary motion of the actuator shaft (21) is converted into the linear motion necessary for the pneumatic control system. The cam disk (22) and the follower roll (20) are used for this purpose.

The positioners operate according to the force-balance principle. The force of the measuring spring (4) is compared to the control force, which produces the pressure pe on the measuring diaphragm (5). If the control signal, the pneumatic input pressure  $(p_e)$  or the position of the lever (1) changes, the diaphragm lever (3) forming the flapper plate varies the distance to the nozzle (2.1 or 2.2). The operating direction (7) selected by the position of the internal turnboard determines which nozzle is effective.

The supply air is piped to the pneumatic amplifier (10) and the pressure regulator (9). The controlled supply flows against the diaphragm lever (3) via the  $X_p$  restriction (8) and the nozzle (2.1 or 2.2). Any changes of the control signal or the position of the lever (1) cause a variation of pressure both upstream and downstream of the amplifier (10). The output signal pressure pst released by the amplifier flows to the pneumatic actuator via the volume restriction (11) and causes the diaphragm or control piston to take a position corresponding to the reference input signal.

If the positioner is to be attached to a double-acting, springless (no spring return) pneumatic rotary actuator, the signal pressure (pst) is to be led to a reversing amplifier, which generates two opposed signal pressures (pst1 and pst2). The adjustable restrictions  $X_p$  (8) and Q (11) are used to optimize the control loop. - Two adjusting screws (6.1 and 6.2) are used to adjust the position of the control valve to the signal pressure. ZERO and SPAN of the reference input signal can be adjusted for deviating operating modes, such as split-range operation. **Operating direction** 

When the reference input signal (pe) increases, the output signal pressure (pst) can be selected to be increasing-increasing (direct action >>) or increasing-decreasing (reverse action <>). The operating direction is determined by how the board (7) is turned, and is shown on the board. Subsequent modification of the operating direction is possible in the field.

#### Legend to Figs. 6 to 8

- 1 Lever 11 Pin
- 1.2 Rotary shaft
- Nozzle, direct action (>>) 2.1
- Nozzle, reverse action (<>) Diaphragm lever (flapper plate) 2.2 3
- 4
- Measuring spring Measuring diaphragm 5
- 6.1 SPAN adjustment screw
- 6.2 7 ZERO adjustment screw
- Turnboard for operating direction
- , 8 9 X<sub>p</sub> restriction (gain) Pressure regulator
- Amplifier (booster) 10
- 11
- 12 Solenoid valve (option)

Electropneum. converter Permanent magnet

- E1 E2
- Plunger coil E3 Balance beam
  - Cross spring pivot
- E4 E5
- Spring Nozzle E6
- E7 Flapper plate E8
- Restriction F9 Damping
- E10 Protective diode

20

21

22

Ε

- Volume restriction Q
- Follower roll Actuator shaft Cam disk

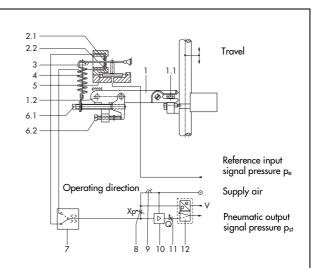


Fig. 6 · Functional diagram of the Type 3766 Pneumatic Positioner (deflection of the pick-off lever when directly attached to the Type 3277 Pneumatic Actuator)

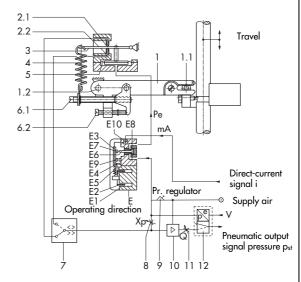
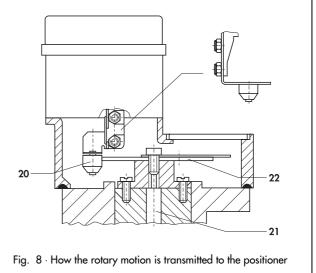


Fig. 7 · Functional diagram of the Type 3767 i/p Positioner



### Table 1 · Technical data · All pressures in bar (gauge)

Type 3766 Pneumatic a	nd Type 3767 Electr	opneumatic Po	sitioners					
Travel range			When directly attached to Type 3277 Pneumatic Actuator: 7.5 30 mm					
			When attached according to IEC 60534 (NAMUR): 7.5 120 mm					
Opening angle		Depending on the cam, 70°, 75° or 90°						
Reference input signal w Signal range bar (psi)			0.2 1 bar (3 15 psi)					
Type 3766 Positioner Span bar (psi) Overload limit to max.					ar (6 12 psi)			
			2 bar (29 psi)					
Reference input signal w			4(0) 20 mA or			1 5 mA		
Type 3767 i/p Positione	<sup>r</sup> Span		8 20 mA			4 mA		
,, ,	Internal resistance c	t 20 °C		0 Ω		80 Ω		
Supply air					r (20 90 psi)			
Output signal pressure			Limitable between 0			ox. 35 and 0 90 psi		
Characteristic				; deviation from term				
Hysteresis			Lindar		).3 %			
Sensitivity					0.1 %			
Operating direction					ersible			
Proportional band X <sub>p</sub>			0.5	2.5 % (proportional		0 401		
Air consumption								
Air consumption	Turne 2744 Death	or .		air 1.4 bar 0 I <sub>n</sub> /h		ıly air 6 bar 30 In/h <sup>1)</sup>		
	Type 3766 Position							
<u></u>	Type 3767 i/p Posi	tioner		0 In/h		80 In/h		
Air output capacity	Add air to actuator			m <sub>n</sub> <sup>3</sup> /h		8.5 m <sub>n</sub> <sup>3</sup> /h		
<b>N</b>	Vent air from actua	for		n <sub>n</sub> 3/h		0 m <sub>n</sub> <sup>3</sup> /h		
Permissible ambient temp	perature		−20 °C with plastic cable gland; −40 °C with metal cable gland <sup>2)</sup> Up to +80 °C (only −20 °C+70 °C with position transmitter)					
Influence		Temperature: ≤ 0.3 %/10 K Supply air: ≤ 1 % between 1.4 6 bar						
Electromagnetic compatil	oility		According to EN 50 081 and EN 50 082					
Effect of vibration		Between 10 and 150 Hz and 4 g, no influence						
Explosion protection <sup>2)</sup>		Type of protection 🐵 II 2 G EEx ia IIC Tó or 🐵 II 3 G EEx nA II Tó for Zone 2						
Degree of protection		IP 54 (special version IP 65)						
Weight		Approx. 1 kg						
Accessories								
Limit switches								
Inductive limit switches (p	proximity switches)			Two Typ	be SJ2-SN			
Control circuit	, ,		Values according to the connected transistor relay					
Switching differential at r	rated travel		$\leq 1\%$					
Solenoid valve								
Electrical input				Binary DC	voltage signal			
Nominal signal		6 V DC	12 V DC		24 V DC			
Signal "0" (off) <sup>3)</sup>		≤ 1.2 V		2.4 V	≤ 4.7 V			
Signal "1" (on) <sup>4)</sup>	•		≤ 1.2 V ≤ 5.4 V		P.6 V	≤ 18.0 V		
Maximum permissible electrical signal					32 V			
Internal resistance R; at 20 °C				5 V     32 V       32 Ω     11714 Ω				
Air consumed in the steady state		Additionally with positioner "off" $\leq 60 \text{ l}_{n}/\text{h} \cdot \text{"on"} \leq 10 \text{ l}_{n}/\text{h}$						
Closing time	Type 3277 Pneuma	tic Actuator	120 cm <sup>2</sup>	240 cm <sup>2</sup>	$350 \text{ cm}^2$	700 cm <sup>2</sup>		
for rated travel and	0.2 1 bar		≤ 0.5 s	≤ 0.8 s	≤ 1.1 s	≤ 4 s		
signal pressure range	0.4 2 bar		≤ 0.5 s	<u> </u>	≤ 2.5 s	≤ 4 s ≤ 8 s		
(K <sub>vs</sub> value 0.14)	0.4 2 bar		<u> </u>	≤ 1 s	≤ 1.5 s	≤ 5 s		
nalog position transmitter			_ 1 3	_ 1.0 3	3			
• •			Two-wi	re system 1 20 ml	direction of action	reversible		
Output Power supply		Two-wire system 420 mA, direction of action reversible     Minimum terminal voltage 12 V, maximum 45 V     The position transmitter may only be connected to a certified intrinsically safe circuit 5			mitter may only be			

1) For minimum adjusted pressure regulator

For minimum acjusted pressure regulator
Special version: Up to -45 °C on request (for Ex-versions, see Table 2)
Direct voltage signal at -25 °C
Direct voltage signal at +80 °C
e.g., via SAMSOMATIC Type 994-0103-CS-412 Loop Isolator or Type 994-0103-CMC-0303-5 Direct-Current Disconnector
Actuator with effective area 120 cm<sup>2</sup> with all signal pressure ranges: ≤ 0.5 s

Electropneumatic converter (Type 3767 i/p Positioner only)						
Maximum values for:	Connection to certified intrinsically safe circuits					
Uo	28 V 25 V					5 V
lo	85 mA 100 mA			nΑ	150	) mA
Р	0.7 W 0.7 W 0.7 W					7 W
Internal inductance and capacitance negligibly small						
Inductive limit switches						
Maximum values for:	Connection to certified intrinsically safe circuits					
Uo			16 V			
lo		52	2 mA/25	5 mA		
Р		169	9 mW/6	4 mW	/	
Internal inductance		L	i = 100	μН		
Internal capacitance	$C_i = 30 \text{ nF}$					
Solenoid valve						
Nominal signal	6 '	V	12 \	/	24 V	
Maximum values for:	Connec circuits	tion to	certified	intrins	sically	' safe
U <sub>0</sub> (V)	25 27 28 30			)	32	
l <sub>0</sub> (mA)	150	125	115	10	0	90
Internal inductance and c	apacitan	ce negl	igibly sm	all		
Analog position transmit	ter					
Maximum values for:	Connection to a certified intrinsically safe circuit					
Uo	28 V					
lo	115 mA					
Р	1 W					
Ci	5.3 nF					
Internal inductance and capacitance negligibly small						
Permissible ambient temperatures						
Temperatures correspond attached to the EC Type I and the Statement of Cor	Examinat	ion Cer	tificate P	TB 01	ATE	X 2167

# Metal tag Switch B Switch B Switch A 34 32 1.2 Metal tag 32 1.2 33 34 Switch A Fig. 9 · Inductive limit switches (proximity switches)

Accessories

The positioners can optionally be equipped with the following accessories.

#### Positioner with inductive limit switches (Fig. 9)

This positioner version has a rotary shaft (1.2) with two adjustable metal tags (33) for inductively actuating the proximity switches (34). The switches are infinitely adjustable and can be overridden. To operate them, corresponding transistor relays are to be connected in the output circuit.

The proximity switches can also be subsequently retrofitted.

#### Positioner with solenoid valve (Fig. 10)

The positioners can be fitted with an intrinsically safe, pilot-controlled solenoid value - also along with the inductive limit switches. When the positioner is equipped with this solenoid valve, the control valve can be moved in the fail-safe position independent of the positioner's output signal.

The solenoid valve essentially consists of an electropneumatic converter (12.1) and a 3/2-way solenoid valve (12.2). If a control signal corresponding to the binary signal 0 (off) is applied to the input, the following occurs: The nozzle (12.3) of the electropneumatic converter is opened; the signal pressure pst is blocked; and air is vented out of the actuator. The force of the compression springs installed in the actuator move the control valve in the predetermined fail-safe position.

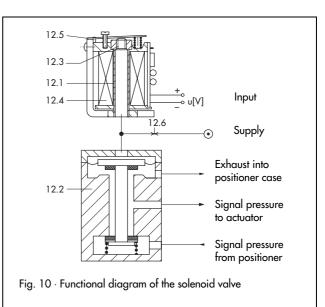
If a control signal corresponding to binary signal 1 (on) is applied to the input, the relay coil (12.4) is energized, and the flapper plate (12.5) closes the nozzle (12.3). The increasing cascade pressure switches over the 3/2-way valve (12.2). In this position, the signal pressure pst is connected through to the actuator. The control valve is in control operation.

The solenoid valve can also be subsequently retrofitted.

#### Legend to Figs. 9 and 10

- Rotary shaft 12 12
- Solenoid valve 12.1 Electropneumatic (e/p) converter
- 12.2 3/2-way solenoid valve
- 12.3 Nozzle 12.4 Relay coil

- 12.5 Flapper plate
- 12.6 Restriction
- Adjusting screw 32
- 33 Metal tag
- 34 Proximity switch



#### Positioner with analog position transmitter

Because of the amount of space that the position transmitter requires, note that this option cannot be combined with installed limit switches or a solenoid valve!

With the position transmitter, the position of the throttling member of the control valve (i.e., valve travel or opening angle) is converted into a proportional output signal from 4 to 20 mA. Three basic types of limit positions are signalized: Control valve opened; control valve closed; and all intermediate positions.

#### Attachment to linear and rotary actuators (Figs. 12 and 13)

With linear-motion actuators, the positioner can be attached either directly (Type 3277 Pneumatic Actuator) or according to IEC 60534 (NAMUR) (Type 3271 Pneumatic Actuator). With rotary-motion actuators, the positioner is attached with an interface according to VDI/VDE 3845, together with an intermediate piece.

#### Combining the positioner and the actuator (Fig. 11)

How the positioner and actuator can be arranged depends on the operating direction of the reference input signal ( $p_e$ ) and the output signal pressure ( $p_{st}$ ), plus the fail-safe position of the actuator, namely:

- Actuator stem "extends"
- Actuator stem "retracts"

#### Direct attachment to Type 3277 Pneumatic Actuator (Fig. 4)

This method of attachment provides the benefit of being a self-contained, preconfigured actuator-positioner unit. Direct attachment of actuator sizes 240, 350 and 700  $\rm cm^2$  requires a connection block (Fig. 11).

With actuator version actuator stem "extends," the loading pressure  $p_{st}$  from the positioner is introduced to the bottom diaphragm case via the connection block and a hole in the actuator yoke. If the spring chamber need be vented with the exhaust air of the positioner, the air can be connected to the connection block using a prefabricated pipe.

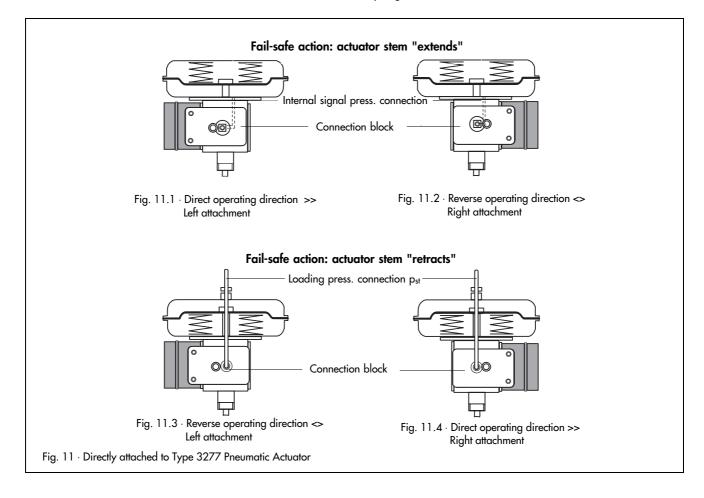
With actuator version actuator stem "retracts," the loading pressure pst from the positioner is introduced to the top diaphragm case via a prefabricated pipe. Air can be exhausted from the bottom diaphragm chamber (spring chamber) without additional measures via an internal hole.

With the Type 3277-5 Pneumatic Actuator (actuator size 120 cm<sup>2</sup>), the loading pressure is connected via a rear hole in the positioner, therefore eliminating external piping.

#### Table 3 · Direct attachment: travel and measuring spring

Actuator size in cm <sup>2</sup>	Travel in mm	Meas. spring
120/240/350	7.5	2
120/240/350	15	1
700	15	2
700	30	1

The positioner is delivered with measuring spring 1; measuring spring 2 can be found in the accessories.



#### Attachment according to IEC 60534 (Figs. 3 and 12)

The positioners can be attached to actuators with casted yokes (Fig. 3) (e.g., Series 240, 250 and 280) and valves with rod-type yokes (Fig. 12) with the aid of the mounting adapter (15). A clamping plate (15.1) is additionally required for valves with rod-type yokes.

By selecting the appropriate lever (1) and link point on the lever (16), the positioners can be matched to different travels in the range from 7.5 to 120 mm.

There is no prescribed mounting position for the positioner. The operating direction is determined by how the positioner and the adapter are arranged and how the internal turnboard is positioned.

The measuring spring is to be selected according to Table 4.

#### Table 4 · Choosing the measuring spring for the travel range required: Attachment according to IEC 60534

Travel mm	Measuring spring
7.5 15	2
> 15 60	1
22 120	1

The positioner is delivered with measuring spring 1; measuring spring 2 can be found in the accessories.

#### Attachment to rotary actuators (Fig. 13)

The positioners can be attached to the Type 3278 Rotary Actuator via an intermediate piece (2). Attachment to other rotary actuators is possible with an interface according to VDI/VDE 3845. Via the cam disk (7), the rotary motion of the actuator is converted into a linear motion required by the positioner. A follower roll (3) is attached to the lever (5) of the positioner in order to detect the cam disk. Various cams are available depending on the control valve characteristic required (e.g., linear or equal percentage).

Double-acting, springless (no spring return) actuators require, in addition, a pneumatic **reversing amplifier** which produces two opposed signal pressures.

#### Choose the measuring spring as follows:

Reference input variable for split-range operation:

- Measuring spring 1

- Reference input variable for normal (full) signal range:
- Measuring spring 2

The positioner is always delivered with measuring spring 1; measuring spring 2 is included in the mounting kit for rotary actuators.

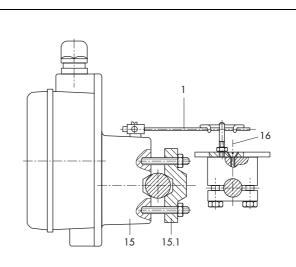
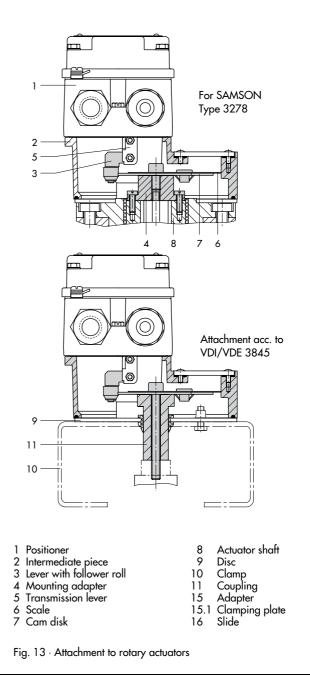


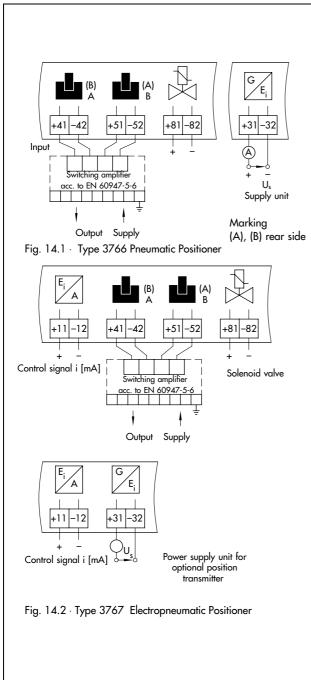
Fig. 12 · Attachment to valves with rod-type yokes



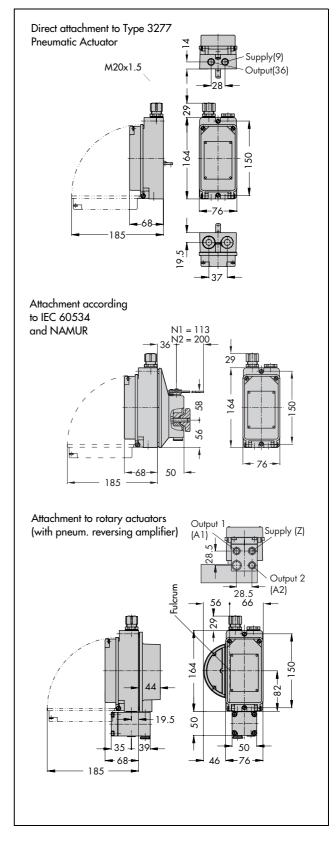
#### Materials (WN = Material Number according to DIN)

Case Special version	Die-cast aluminum chromized and plastic-coated CrNiMo steel, WN 1.4404 (316 L)
External parts	Stainless steel WN 1.4571 and WN 1.4305
Measuring diaphragm	Fluorosilicone rubber

#### **Electrical connections**



#### Dimensions in mm



Certificate type	Certificate number	Date	Comments
EC Type Exam. Certificate	PTB 01 ATEX 2171	2001-11-26	🐵 II 2 G EEx ia IIC T6
Statement of Conformity	PTB 01 ATEX 2195 X	2002-03-07	🐵 II 3 G EEx nA II Tó
Certificate of Conformity	PTB No. Ex-89.C.2165	1989-11-06	EEx ia IIC T6
First Addendum		1991-02-12	Position transmitter
Second Addendum	-	1992-01-17	Higher Ex i parameters
Third Addendum	-	1993-11-22	-45 °C ambient temperature
Fourth Addendum	-	1995-06-13	Round connector
Fifth Addendum		1997-07-11	Solenoid valve, position transmitter
SEV Certificate	98.5. 50771.04	1998-04-24	EEx ia IIC T4, T5
GOST Certificate	2002.C299	2002-12-26	1 Ex ia IIC T6 X; valid until 2008-01-01
CZ Certificate	08.85.0292/J03058	1995-11-08	EEx ia IIC T6; valid until 1998-12-31
CSA Certificate	LR 54227-11	1991-01-29	Class I; Groups A, B, C, D
Enclosure 3		1992-04-21	Class I; Div. 2; Groups A, B, C, D
	LR 54227-17	1993-02-03	Position transmitter
	LR 54227-27	1997-09-17	Groups A, B, C, D
FM Certificate	J.I. 2 V 9 A9.AX	1991-11-18	Class I, II, III; Div. 1, Groups A, B, C, D, E, F, G
	J.I. 4W9 A0.AX	1993-04-22	Position transmitter
		1998-10-20	Revision position transmitter
NEMA 3R	J.I. OW 4 A0.AX	1991-02-19	

Please refer to Data Sheet T 6116 EN for EEx d certification for the Type 6116 i/p Converter (Fig. 2).

## Summary of the approved explosion protection certificates for the Type 3767 Positioner

Certificate type	Certificate number	Date	Comments	
EC Type Exam. Certificate	PTB 01 ATEX 2167	2001-11-29	🐵 II 2 G EEx ia IIC Tó	
Statement of Conformity First Addendum	PTB 01 ATEX 2170 X	2002-03-07 2003-05-28	🐵 II 3 G EEx nA II T6; Type 3767-8 Zone 2	
Certificate of Conformity	PTB No. Ex-89.C.2166	1989-11-06	EEx ia IIC T6	
First Addendum		1991-02-12	Position transmitter	
Second Addendum		1992-01-17	Higher Ex i parameters	
Third Addendum		1993-01-15	Additional Ex i values	
Fourth Addendum		1993-11-22	-45 °C ambient temperature	
Fifth Addendum		1995-06-13	Type of connection altered	
Sixth Addendum		1997-07-11	Internal design and nameplate altered	
SEV Certificate	98.5 50771.05	1998-04-24	EEx ia IIC T4, T5	
GOST Certificate	2002.C299	2002-12-26	1 Ex ia IIC T6 X; valid until 5008-01-01	
CZ Certificate	08.95.0293/J03059	1995-11-08	EEx ia IIC T6; valid until 1998-12-31	
BKI Certificate	Ex-98-C.001		EEx ia IIC T4, T5, T6	
First extension		2002-02-23	valid until 2003-06-30	
CSA Certificate	LR 54227-11	1991-01-29	Class I; Groups A, B, C, D	
		1992-04-21	Class I; Div. 2	
	LR 54227-17	1993-02-03	Position transmitter	
	LR 54227-26	1997-09-17	Div. 1; Groups A, B, C, D, E, F, G	
FM Certificate	J.I. 2 V 9 A9.AX	1991-11-18	Class I, II, III; Div. 1; Groups A, B, C, D, E, F, G	
NEMA 3R	J.I. OW 4 A0.AX	1992-02-19		
FM Certificate	J.I. 4 W 9 A0.AX	1993-04-22	Position transmitter	
	J.I. 5Y2 A3.AX	1995-04-26	Div. 2	
		1998-10-20	Revision position transmitter	
AUS Certificate	1478 X	1993-08-04	Ex ia IIC T6, Class I, Zone 0	
	EX 1482	1993-08-04	Ex n IIC T6, Class I, Zone 2	
JIS Certificate	C-13674	2002-07-11	Ex ia IIC T6; extension	

Nomenclature for ordering	Ac
Type designation     3766-     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓     ↓	
3/6/- II II II 0 I II IIExplosion protectionWithout	JUJJ Me Ad Wi an Sp Ad Or rev Sp Me Me Ac Ac
ISO 288/1-G <sup>1</sup> / <sub>4</sub> 2	Sp
Electrical connection	Tro
without (Type 3766 without accessories only) M 20x1.5 blue M 20x1.5 black 2	Tro
Special version None Enclosure made of CrNiMo steel Reference input signal (only for Type 3767) 4 to 20 mA 0 to 20 mA 1 to 5 mA	0 Sp 0 Ac 2 Ro 1 Ro 2 Wi 3 Wi 0p

Positioner **only** functioning as an analog position transmitter  $3766 \square 6 0 0 0 0 \square 0 9 0$ 

#### Accessories

Adapter to NPT 1/2 for the electrical connections Measuring spring 2

Additional specifications

Without/with pressure gauge for monitoring the signal pressure and supply air

Specify when mounting on a control valve: Adjusted reference input signal Operating direction: direct (increasing-increasing) or reverse (increasing-decreasing)

Specify for devices with inductive limit switches: Metal tag in the active zone (contact closed)/ Metal tag out of the active zone (contact open)

Specify for direct attachment to the Type 3277 Pneumatic Actuator:

Actuator size: 120/240/350/700 cm<sup>2</sup>

Specify for attachment according to IEC 60534-6 (NAMUR): Travel: ...mm

Specify for attachment to valves with rod-type yokes: Travel: ...mm Rod diameter: ...mm

Specify for attachment to Type 3278 Rotary Actuators: Actuator sizes 160 or 320 cm<sup>2</sup> Rotary actuator according to VDI/VDE 3845, single-acting or Rotary actuator according to VDI/VDE 3845, double-acting With linear control valve characteristic With equal percentage control valve characteristic

Opening angle 70°/75°/90°

When the positioner is delivered without a specific arrangement to a certain control valve, refer to the "Mounting and operating instructions" EB 8355-1 EN (for Type 3766 Pneumatic Positioner) or EB 8355-2 EN (for Type 3767 Electropneumatic Positioner).

Specifications subject to change without notice.

